Robotics Engineering, B.S.

Degree Offered

• Bachelor of Science in Robotics Engineering (B.S.)

Nature of the Program

Robotics engineering ranks amongst the fastest-growing profession globally according to a recent World Economic Forum Future of Jobs Report. This four-year degree program explores mechanical systems, computer science and engineering systems to provide students with a strong interdisciplinary foundation. Through the fundamentals of robotics systems, mobile robotics, robotic manipulators and autonomy students gain the knowledge and skills to develop their own robotics solutions. The culmination of this program is through the development of a yearlong capstone project giving students the experience to be prepared for a career in robotics engineering within the growing industry, government position or academia.

The robotics engineering program is designed to equip students with the knowledge and skills to excel in the engineering design and production of robotics and autonomous systems solutions. The program will prepare next-generation robotics engineers who are:

- Effective in the engineering design and production of robotics and autonomous systems solutions to alleviate the burden of human workload or create safer work environments.
- Versed to apply a theoretical foundation of mechanical, electrical and computer engineering systems to integrate and devise robotics solutions.
- Educated and trained to apply robotics solutions in collaboration with specialists in the field, ensuring a comprehensive and interdisciplinary approach to addressing challenges in robotic systems.

General Education Foundations

Please use this link to view a list of courses that meet each GEF requirement. (http://registrar.wvu.edu/gef/)

NOTE: Some major requirements will fulfill specific GEF requirements. Please see the curriculum requirements listed below for details on which GEFs you will need to select.

| Code | Title | Hours |
|---------------------------------------|---|-------|
| General Education Foundations | | |
| F1 - Composition & Rhetoric | | 3-6 |
| ENGL 101 & ENGL 102 or ENGL 103 | Introduction to Composition and Rhetoric and Composition, Rhetoric, and Research Accelerated Academic Writing | |
| F2A/F2B - Science & Technology | | 4-6 |
| F3 - Math & Quantitative Reasoning | | 3-4 |
| F4 - Society & Connections | | 3 |
| F5 - Human Inquiry & the Past | | 3 |
| F6 - The Arts & Creativity | | 3 |
| F7 - Global Studies & Diversity | | 3 |
| F8 - Focus (may be satisfied by com | npletion of a minor, double major, or dual degree) | 9 |
| Total Hours | | 31-37 |

Please note that not all of the GEF courses are offered at all campuses. Students should consult with their advisor or academic department regarding the GEF course offerings available at their campus.

Degree Requirements

Students must meet the following criteria to qualify for a Bachelor of Science in Robotics Engineering degree:

- Complete a minimum of 124 credit hours
- · Satisfy WVU's undergraduate degree requirements
- Satisfy Statler College's undergraduate degree requirements (http://catalog.wvu.edu/undergraduate/collegeofengineeringandmineralresources/ #policiestext)
- · Complete all courses listed in the curriculum requirements with the required minimum grades
- Attain an overall grade point average of 2.00 or better
- Attain a WVU grade point average of 2.00 or better

- · Attain a Statler grade point average of 2.00 or better
- A maximum of one math or science course with a grade of D+, D, or D- may be applied toward degree completion
- Complete a survey regarding their academic and professional experiences at WVU, as well as post-graduation job placement or continuing education plans.

The Statler GPA is computed based on all work taken at WVU with a subject code within Statler College (BIOM, BMEG, CE, CHE, CPE, CS, CSEE, CYBE, EE, ENGR, ENVE, ETEC, IENG, IH&S, MAE, MINE, PDA, PNGE, ROBE, SAFM, SENG) excluding ENGR 140, ENGR 150, and CS 101. The WVU GPA is computed based on all work taken at WVU. The Overall GPA is computed based on all work taken at WVU and transfer work.

Curriculum Requirements

| Code | Title | Hours |
|----------------------------------|-----------|-------|
| University Requirements | | 16 |
| Fundamentals of Engineering Requ | irements | 2 |
| Math and Science Requirements | | 28 |
| Robotics Engineering Program Req | uirements | 78 |
| Total Hours | | 124 |

University Requirements

| Code | Title | Hours |
|---|---|-------|
| General Education Foundations (| GEF) 1, 2, 3, 4, 5, 6, 7, and 8 (31-37 Credits) | |
| Outstanding GEF Requirements 1, 5, 6, 7 | | 15 |
| ENGR 191 | First-Year Seminar | 1 |
| Total Hours | | 16 |

Fundamentals of Engineering Requirements

| Code | Title | Hours |
|-----------------------|---|-------|
| A minimum grade of C- | is required in all Fundamentals of Engineering courses. | |
| ENGR 101 | Engineering Problem Solving 1 | 2 |
| Total Houro | | 2 |

Total Hours

Math and Science Requirements

| Code | Title | Hours |
|--------------------------------------|---|-------|
| A minimum grade of C- is required | in all Math and Science courses. | |
| Lab Science (select one of the follo | owing): | 4 |
| CHEM 115 & 115L | Fundamentals of Chemistry 1 and Fundamentals of Chemistry 1 Laboratory | |
| BIOL 115 & 115L | Principles of Biology and Principles of Biology Laboratory | |
| GEOL 101 & 101L | Planet Earth and Planet Earth Laboratory | |
| Calculus I (GEF 3): | | 4 |
| MATH 155 | Calculus 1 | |
| MATH 153 & MATH 154 | Calculus 1a with Precalculus and Calculus 1b with Precalculus | |
| MATH 156 | Calculus 2 | 4 |
| MATH 251 | Multivariable Calculus | 4 |
| MATH 261 | Elementary Differential Equations | 4 |
| PHYS 111 | General Physics 1 | 4 |
| & 111L | and General Physics 1 Laboratory | |
| PHYS 112 & 112L | General Physics 2 and General Physics 2 Laboratory | 4 |
| Total Hours | | 29 |

Total Hours

Robotics Engineering Program Requirements

| Code | Title | Hours |
|---------------------------------------|---|-------|
| ECON 201 | Principles of Microeconomics | 3 |
| EE 221 & 221L | Introduction to Electrical Engineering and Introduction to Electrical Engineering Laboratory | 4 |
| EE 251 & 251L | Digital Electronics and Digital Electronics Laboratory | 4 |
| CS 110 & 110L | Introduction to Computer Science and Introduction to Computer Science Laboratory | 4 |
| CS 111 & 111L | Introduction to Data Structures and Introduction to Data Structures Laboratory | 4 |
| CPE 271 & 271L | Introduction to Digital Logic Design and Digital Logic Laboratory | 4 |
| MAE 202 | Sophomore Seminar | 1 |
| MAE 211 & 211L | Mechatronics and Mechatronics Laboratory | 3 |
| MAE 212L | Introduction to Computer Aided Design | 1 |
| MAE 241 | Statics | 3 |
| MAE 242 | Dynamics | 3 |
| MAE 243 | Mechanics of Materials | 3 |
| MAE 244L | Dynamics and Strength Laboratory | 1 |
| CS 350 | Computer System Concepts | 3 |
| CPE 310 | Microprocessor Systems | 4 |
| & 310L | and Microprocessor Systems Laboratory | |
| MAE 342 | Dynamics of Machines | 3 |
| MAE 411 | Advanced Mechatronics | 3 |
| & 411L | and Advanced Mechatronics Laboratory | |
| MAE 460 | Automatic Controls | 3 |
| ROBE 313 | Fundamentals of Robotic Systems | 3 |
| ROBE 412 | Mobile Robotics | 3 |
| ROBE 413 | Robotic Manipulators | 3 |
| ROBE 414 | Robot Autonomy | 3 |
| ROBE 471S | Principles of Engineering Design | 3 |
| ROBE 472S | Engineering Systems Design | 3 |
| Technical Elective (Choose two of the | | 6 |
| CPE 442 | Introduction to Digital Computer Architecture | |
| EE 327 | Signals and Systems 1 | |
| EE 355 | Analog Electronics | |
| & 355L | and Analog Electronics Laboratory | |
| IENG 405 | Design for Manufacturability | |
| IENG 445 | Project Management for Engineers | |
| MAE 312 | Introduction to Mechanical Design | |
| MAE 473 | Bioengineering | |
| or BMEG 340 | Biomechanics | |
| or BIOM 425 | Bioengineering | |
| MAE 491 | Professional Field Experience | |
| or MAE 495 | Independent Study | |
| or MAE 496 | Senior Thesis | |
| MATH 441 | Applied Linear Algebra | |
| PHYS 314 | Introductory Modern Physics | |
| PHYS 321 | Optics | |

PHYS 332

Theoretical Mechanics 2

Total Hours

78

Suggested Plan of Study

| 00 | • | | |
|------------------------|-------|--------------------------|-------|
| First Year | | | |
| Fall | Hours | Spring | Hours |
| CS 110 | | 4 CS 111 | |
| & 110L | | & 111L | |
| ENGL 101 | | 3 MATH 156 | 4 |
| ENGR 101 | | 2 PHYS 111 | 2 |
| | | & 111L | |
| ENGR 191 | | 1 GEF 5 | 3 |
| MATH 155 | | 4 | |
| Lab Science | | 4 | |
| | | 18 | 15 |
| Second Year | | | |
| Fall | Hours | Spring | Hours |
| EE 221 | | 4 MAE 211 | 3 |
| & 221L | | & 211L | |
| MAE 202 [*] | | 1 MAE 212L | |
| MAE 241 | | 3 MAE 242 | 3 |
| MATH 251 | | 4 MATH 261 | 4 |
| PHYS 112 | | 4 ENGL 102 | 3 |
| & 112L | | | |
| | | 16 | 14 |
| Third Year | | | |
| Fall | Hours | Spring | Hours |
| MAE 243 | | 3 ECON 201 | 3 |
| MAE 244L | | 1 EE 251 | 4 |
| | | & 251L | |
| GEF 6 | | 3 MAE 342 | 3 |
| CS 350 | | 3 ROBE 313 | 3 |
| CPE 271 | | 4 CPE 310 | 2 |
| & 271L | | & 310L | |
| | | 14 | 17 |
| Fourth Year | | | |
| Fall | Hours | Spring | Hours |
| MAE 411 | | 3 MAE 460 | 3 |
| & 411L [*] | | | |
| ROBE 412 [*] | | 3 GEF 7 | 3 |
| ROBE 414 [*] | | 3 ROBE 413 [*] | 3 |
| ROBE 471S [*] | | 3 ROBE 4728 [*] | 3 |
| Technical Elective | | 3 Technical Elective | 3 |
| | | 15 | 15 |

Total credit hours: 124

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Offered once per year in the semester shown.

Major Learning Outcomes ROBOTICS ENGINEERING

Upon graduation, all Bachelor of Science students in Robotics Engineering will have acquired the:

- Students will be effective in the engineering design and production of robotics and autonomous systems solutions to lighten the burden of human work;
- Students will be able to apply a theoretical foundation of mechanical systems, electrical systems and computer engineering systems to integrate and devise robotics solutions;
- Student will be effective and planning the use of and participating in the development of robotics and autonomous systems; and
- Students will have the education and training to apply robotics solutions in concert with specialists who deal with robotic systems.